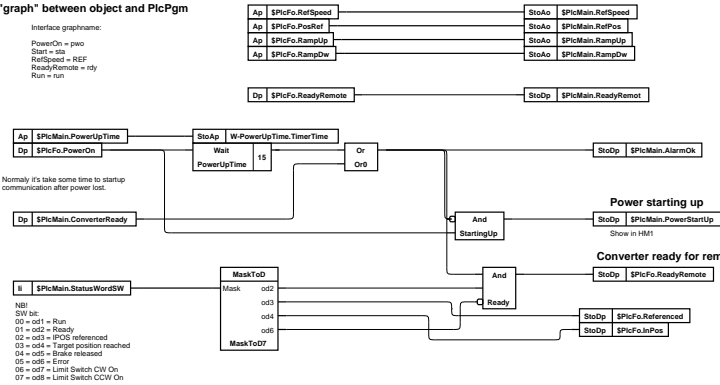


Interface "graph" between object and PicPgm

Interface graphname:
PowerOn = po
Start = stb
RefSpeed = rfr
ReadyRemote = rdy
Run = run



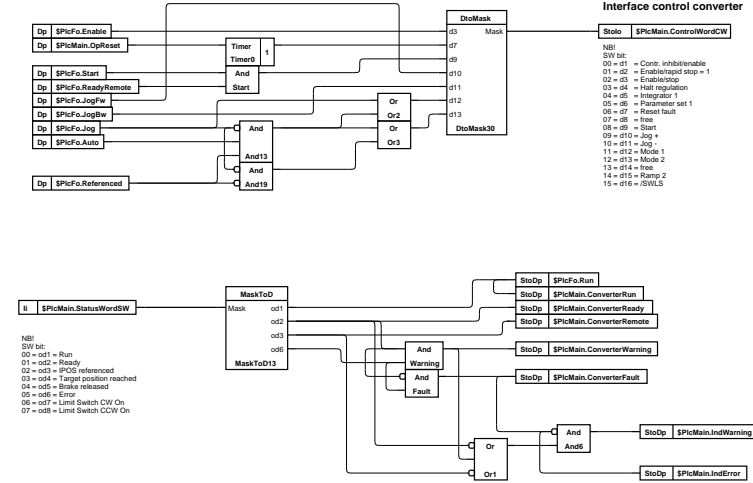
Normally it's takes some time to startup communication after power lost.

NBI
SW bit:
00 = 001 = Run
01 = 002 = Ready
02 = 003 = IPOS referenced
03 = 004 = Target position reached
04 = 005 = Brake released
05 = 006 = Error
06 = 007 = Limit Switch CW On
07 = 008 = Limit Switch CCW On

Functionobject
SEW Movidrive MDX60B/61B Type 1 version 1
Speedcontrol, SEW drives comm. profile,
Profibus communication.

Class-SEW_Movidrive_EPBFo-Code	
W	Proview
19-APR-2007 15:22	

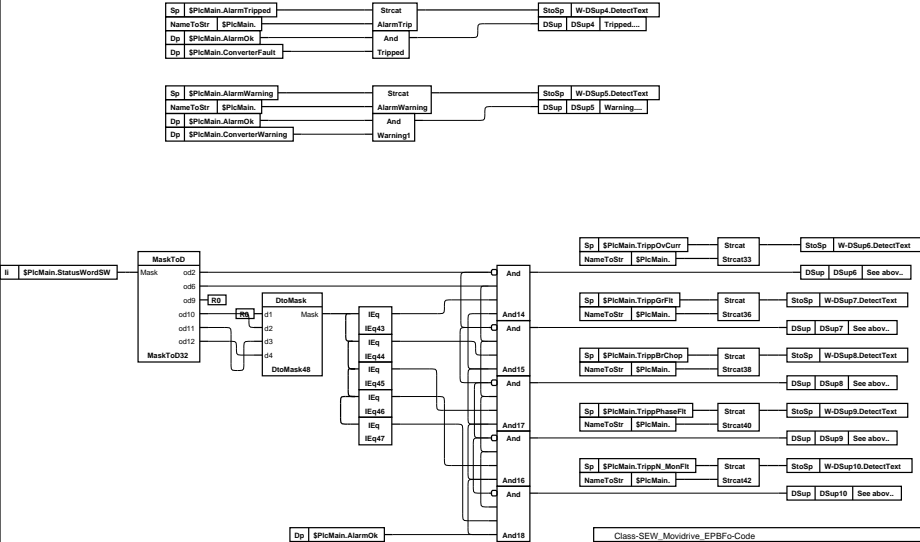
Interface control converter



NBI
SW bit:
00 = 001 = Run
01 = 002 = Ready
02 = 003 = IPOS referenced
03 = 004 = Target position reached
04 = 005 = Brake released
05 = 006 = Error
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Functionobject
SEW Movidrive MDX60B/61B Type 1 version 1
Speedcontrol, SEW drives comm. profile,
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Class-SEW_Movidrive_EPBFo-Code	
W	Proview
19-APR-2007 15:22	



Class-SEW_Movidrive_EPBFo-Code	
W	Proview
19-APR-2007 15:22	